#include <Servo.h>

Servo M1;

Servo M2;

int M1\_pin = 2;

int M2\_pin = 3;

int lazerPin = 13;

int Th1, Th2, tmp;

void setup() {

  Serial.begin(9600);

  pinMode(lazerPin,OUTPUT);

  M1.attach(M1\_pin);

  M2.attach(M2\_pin);

  pinMode(lazerPin, OUTPUT);

  digitalWrite(lazerPin, HIGH);

}

void loop() {

  if(Serial.available()>=2)

  {

    Th1 = Serial.read();

    Th2 = Serial.read();

    while(Serial.available()) tmp = Serial.read();

        M1.write(Th1);

        M2.write(Th2);

  }

}